

# ROBOTICS

# IRB 120

ABB's 6 axis robot – for flexible and compact production



The IRB 120 robot is the latest addition to ABB's new fourthgeneration of robotic technology. It is ideal for material handling and assembly applications and provides an agile, compact and lightweight solution with superior control and path accuracy.

#### Compact and lightweight

IRB 120's compact design enables it to be mounted virtually anywhere at any angle without any restriction - for example inside a cell, on top of a machine or close to other robots.

IRB 120 is also the most portable and easy to integrate on the market with its 25 kg weight. The smooth surfaces are easy to clean and the cables for air and customer signals are internally routed, all the way from the foot to the wrist, ensuring that integration is effortless.

#### Multipurpose

IRB 120 is ideal for a wide range of industries including the electronic, food and beverage, machinery, solar, pharmaceutical, medical and research sectors.

The Food Grade Lubrication (NSF H1) option includes Clean Room ISO Class 5, which ensures uncompromising safety and hygiene for food and beverage applications.

### **Optimized working range**

IRB 120 has a horizontal reach of 580 mm, the best in class stroke, the ability to reach 112 mm below its base and a very compact turning radius.

### Fast, accurate and agile

Designed with a light, aluminum structure, the motors ensure the robot is enabled with a fast acceleration, and can deliver accuracy and agility in any application.

## IRC5 Compact controller – optimized for small robots

ABB's new IRC5 Compact controller presents the capabilities of the IRC5 controller in a compact format. It brings accuracy and motion control to applications which have been exclusive to large installations and enables easy commissioning through one phase power input, external connectors for all signals and a builtin expandable 16 in, 16 out, I/O system.

RobotStudio for offline programming enables manufacturers to simulate a production cell to find the optimal position for the robot, and provide offline programming to prevent costly downtime and delays to production.

## **Reduced footprint**

The combination of the new lightweight architecture of the IRB 120 with the new IRC5 Compact controller introduces a significantly reduced footprint.

# Specification

Robot version	Reach (m)	Handling capacity (kg)	Armload (kg)
IRB 120-3/0.6	0.58	3*	0.30
Number of axes	6		
Protection	IP30		
Mounting	Any angl	e	
Controller	IRC5 Compact/IRC5 Single Cabinet		
Integrated signal supply	10 signals on wrist		
Integrated air supply	4 air on wrist (5 bar)		
* 4 with vertical wrist			

## Movement

Working range

Axis movement	Working range	Velocity IRB 120
Axis 1 rotation	+165° to -165°	250°/s
Axis 2 arm	+110° to -110°	250°/s
Axis 3 arm	+70° to -110°	250°/s
Axis 4 wrist	+160° to -160°	320°/s
Axis 5 bend	+120° to -120°	320°/s
Axis 6 turn	Default: +400° to -400° Max. rev: +242 to -242	420°/s

#### Performance (according to ISO 9283)

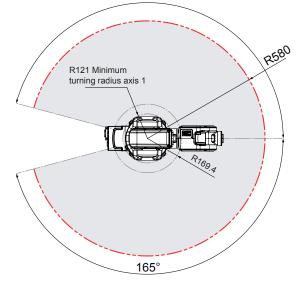
	IRB 120	
1 kg picking cycle		
25 x 300 x 25 mm	0.58 s	
25 x 300 x 25 with 180° axis 6 reorientation	0.92 s	
Acceleration time 0-1 m/s	0.07 s	
Position repeatability	0.01 mm	

# Technical information

Electrical Connections		
Supply voltage	200-600 V, 50/60 Hz	
Rated power	3.0 kVA	
transformer rating		
Power consumption	0.24 kW	
Physical		
Robot base	180 x 180 mm	
Robot height	700 mm	
Robot weight	25 kg	
Environment		
Ambient temperature for	robot manipulator:	
During operation	+5°C (41°F) to +45°C (113°F)	
During transportation and storage	-25°C (-13°F) to +55°C (131°F)	
During short periods (max. 24 h)	up to +70°C (158°F)	
Relative humidity	Max. 95%	
Noise level	Max. 70 dB (A)	
Safety	Safety and emergency stops 2-channel safety circuits super- vision, 3-position enabling device	
Emission	EMC/EMI-shielded	
Options	Clean Room ISO class 5 (certified by IPA)**	

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165°



\*\* ISO class 4 can be reached under certain conditions.

Data and dimensions may be changed without notice.

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